MC-980MA Service Manual

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1. Mode

1.1 Adjustable items of each mode

MC-980 is operated by these three modes.

- Normal mode Usual mode
- Service mode Calibration mode

Service person only (Released by entering a service password P.3) Service person only (Released by removing seal and switching. P.3)

Adjustable items of each mode

	Normal	Service	Calibration
Date and Time	Х	Х	
Printer	Х		
PC Connection	Х		
External Device	Х		
Measurement mode	Х		
Controller	Х	Х	Х
System		Х	Х
Scale		Х	Х
Span Adjustment			Х
Gravity Correct			Х
Count Mode		Х	Х
Scale Mode	Х	Х	Х
Version information		Х	Х
Impedance		X	X
History		X	X
Initialization		X	Х

Page		
P.4	Date and Time	Set date and time
Instruction	Printer	Select printer, Set printer operation
Instruction	PC Connection	Select Baud rate, Flow control
Instruction	External Device	Set barcode reader etc.
Instruction	Measurement Mode	Result Number Athletic selection, Target setting
P.21	Controller	Brightness, Beep, monitor vibration
P.5	System	Regression(Asian / Global), 5V power supply (on / off)
P.6	Scale	
P.6	Set Span	Span adjustment
P.8	Gravity Correct	Gravity correction
P.9	Count Mode	Checking raw count value
P.10	Scale Mode	Measurement weight in Service / Calibration mode
P.11	Version information	Display internal software version number
P.12	Impedance	Display impedance data, Impedance adjustment
P.13	History	Latest adjusted date, Number of adjustment etc
P.14	Initialization	Reset to factory default



2. Various setting 2.1 Date and Time



2.2 S	ystem setting	
	DISPLAY	Operation
7	Maintenance 30/09/2010	Select "System"
Mai	Data and Tara	
nt	Date and Time	
ena	System	
and	Scale	
ce	Version	
	Impedance	
	History	
	Initialization	
	Controller	
	① Shutdown ④ Back	
Ma	Maintenance System 24/09/2010	1. Select regression formula
aint		"Global"
ten	FatS regression + pation	"Asian" from India, Pakistan and to the East
lanc		2. Set On / Off 5V power supply via RS232C cable Note: Fix to "OFF"
e S	Spleet RSSV.	
ÿŝ	2.	3. after inputting, press "OK"
ite		Note:
В		"OK" Save input value
		Back Quit Return without saving
	Toot Print OK AN Back A Quit	
	Test Frint OK No Back Quit	

2.3 Scale setting

2.3.1. Span adjustment

2.0.1		
	DISPLAY	Operation
Maintenance	Maintenance 21/01/2010 Date and Time System Scale Version Unpedance History Initialization Touch Panel	Select "Scale"
	Exit MC-98	U Select "Set Span"
Maintenance Scale	Set Span Gravity Correct Count Mode Scale Mode	
	Back	
Maintenance Span	Maintenance Span 3. 2 30/09/2010 Gravitational Acceleration 8 9 1. 8 9 (3.755 8).892) 4 5 (3.755 8).892) 1 2 1. 8 9 (3.755 8).892) 1 2 1. 9 1 2 (3.755 8).892) 1 2 3 0 1 2 3 0 1 2 3 4. Expension prime Clean Enter	 Input gravitational acceleration 1. Select 9.802 2. Ten key appears 3. Input gravitational acceleration of adjusting area. 9.768 ≤ value ≤ 9.832 4. After inputting, press "Enter Note Netherlands gz = 9,813 m/s2 Akita gz = 9,802 m/s2
Maintenance Span	Maintenance Span 3. 2. severation A. State 4. 6. 4. State 0. 0. 4. State State 0.	Input adjustment load value 1. Select 300 2. Ten key appears 3. Input adjustment load value 20 ≤ value ≤ 300 kg 4. After inputting, press "Enter

			-
	Maintenance Span	05/03/2010	Scale get zero point
			The following message appears
	Gravitational Angeleration 9. 002		"Now detecting zero point.
	Adjustment Weight 500	ku	
			After getting zero point, the following message appears
			"Carry load. Press OK after it stabilized"
	Now detecting yorn point. Please wait.		
	Back	Quit	
	Maintenance Span	05/03/2010	1. Put the adjustment load weight
2			2. After stabilizing, press "OK"
lai	Gravitational Aracheration 9.002		3. Take a load off the scale
nte	Adjustment Weight 500	kg	Neter
'na			Note: "OK" Save span adjustment
nc			"Back" "Quit" Return without saving
e S	furry had.		
pa	Press OK after it stabilized.		
Э			
	OK Back	Quit	
	Maintenance Count Mode	30/09/2010	Raw count value are displayed
			Put the weight, and confirm whether scale is normally
	Before	0	adjusted.
	Correction	Č.	
	After Correction	0	
	Bernarian Darranam		
	👋 Bac	k 🐣 Quit	
	👋 Bac	k 👍 Quit	
	Acceptable televeres	k 🕂 Quit	
	Acceptable tolerance 0 ≤ m	k - <u></u> Quit	0.5m (10cts)
	Acceptable tolerance 0 ≤ m 500 < n	k - <u></u> Quit n ≤ 500 n ≤ 2000	0.5m (10cts) 1.0m (20cts)
	Acceptable tolerance 0 ≤ m 500 < n 2000 < n	k -2^{-2} Quit $n \le 500$ $n \le 2000$ $n \le 10000$	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)
	Acceptable tolerance 0 ≤ m 500 < n	k - (2^{-1}) Quit n ≤ 500 n ≤ 2000 n ≤ 10000	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)
	Acceptable tolerance $ \begin{array}{c} 0 \leq m \\ 500 < n \\ 2000 < n \\ 0 \\ 1e = 0.1 kg \end{array} $	k - <u></u> Quit n ≤ 500 n ≤ 2000 n ≤ 10000	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)
	Acceptable tolerance $ \begin{array}{c} 0 \leq m \\ \hline 0 \leq m \\ \hline 0 \leq m \\ 2000 < n \\ \end{array} $ MC-980 1e = 0.1kg Max = 300kg 60	k -2^{-2} Quit $n \le 500$ $n \le 2000$ $n \le 10000$ 20cts 0000cts	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)
	Acceptable tolerance $ \begin{array}{c} 0 \leq m \\ 500 < m \\ 2000 < m \\ 0 \end{array} $ MC-980 1e = 0.1kg Max = 300kg 60	k - ∴ Quit $n \le 500$ $n \le 2000$ $n \le 10000$ 20cts 0000cts	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)
	Acceptable tolerance $ \begin{array}{c} 0 \le m\\ 500 < n\\ 2000 < n\\ MC-980\\ 1e = 0.1kg\\ Max = 300kg 60 \end{array} $	k -2^{-2} Quit $n \le 500$ $n \le 2000$ $n \le 10000$ 20cts 0000cts	0.5m (10cts) 1.0m (20cts) 1.5m (30cts)





2.3.4. Scale Mode Measurement weight in Service / Calibration mode DISPLAY Operation Select "Scale" Maintenance 21/01/2010 Maintenance Date and Time System Scale Impedanc Exil MC-980 Select "Scale Mode" **Maintenance Scale** 21/01/2010 **Maintenance Scale** Back Weight Measurement weight Weight 24/09/2010 Slep on with care lear COCOCOC Name Gande Тура V/eight Cicinas Vieigra P Registered User 4) Back 🔶 Quit 雷言

2.4 V	ersion information	
Displa	ay internal software version number	
Maintenance	Maintenance 21/01/2010 Date and Time System Scale Version Impedance History Initialization Touch Panel Exit MC-980	Select "Version"
Maintenance Version	Maintenance Version 30/09/2010 P0 Applicator M09809701 Date 2016/09/28 State Control M09809211 Date 2016/09/15 Impedance AD M0980 Date 2010/07/21 State AD S02409201 State AD S02409201	Internal software version numbers are displayed

2.5 Ir	npedance adjustment	
2.5.1	. Check impedance	
	DISPLAY	Operation
Maintenance	Maintenance 21/01/2010 Date and Time System Scale Version Unpedance History Initialization Touch Panel Exit MC-980	Select "Impedance"
Maintenance Impedance	Maintenance Impedance 30/04/2010 Impedance Display Impedance Adjustment Impedance Adjustment Impedance Adjustment Impedance Back Impedance Adjustment	Select "Impedance Display"
Impedance Display	Impedance Display 30/09/2010 Pequency 50kHz 10 100kHz 11 100kHz 12 100kHz 12 100kHz 12 100kHz 2 100kHz 2 100kHz 2 800.20 Phase 0.05 3 800.30 2 800.30 4 Back	 Select measurement frequency Select measurement segmental part Measurement impedance Raw impedance value are displayed



- (2) Impedance adjustment
- 1. Put impedance adjuster on top of the scale.



- Note: The contact points of adjuster (4 contact points) must be attached on each electrode. The electrode is easily scratched. Take care about handling. The impedance adjuster is necessary to put to the right and left correctly.
- 2. Set standard resistor and 500g weight on the impedance adjuster.



Note: Match the L R position of the impedance adjuster and resistor correctly. Put the 500g weight on the adjuster for sturdy touch between contact points and electrode. The standard resistor to use impedance adjustment is 200Ω, 600Ω, 800Ω and 1200Ω.

3. Set the Hand grips on the impedance adjuster.



Note: Open the rubber cover, and insert two connector contacts. The hand grips direction like photograph.





(4) Tolerance													
		Impe	dance						Reactand	ce Resista	ance		
						Low	Middle	Hiah					
											Re: 1500	Re: 3000	Re: 7500
			Re	esistance	of stand	dard	1				Ri: 7500	Ri: 18000	Ri: 27000
											Cm:	Cm:	Cm:
			150Ω	400Ω	800Ω	1500Ω					2700pF	1500pF	1000pF
Seament	Frea.			Tole	rance		l I	Seament	Frea.			Tolerance	
eegmen	1kHz	7	+2%	+2%	+2%	+2%		oogiiioiii	1kHz	RX	+80	+150	+300
	5447	7	+2%	+2%	+2%	+2%			5447	P Y	+80	+150	+300
		7	120/	±2 /0	±2 /0	120/		-			1002	±150	±3002
<u>ц</u> і			±2%	±1%	±1%	±2%		шт			±00	±15Ω	±3002
□-∟	250KHZ	<u></u>	±2%	±2%	±2%	±2%			250KHZ	R, X	±80	±15Ω	±30Ω
	500kHz	Ζ	±3%	±3%	±3%	±3%			500kHz	R, X	±8Ω	±15Ω	±60Ω
	1000kH	Z	±10%	±10%	±10%	reference			1000kH	R, X	±16Ω	±30Ω	reference
	Z								Z				
	1kHz		±2%	±2%	±2%	±2%			1kHz	R, X	±8Ω	±15Ω	±30Ω
	5kHz	Ζ	±2%	±2%	±2%	±2%			5kHz	R, X	±8Ω	±15Ω	±30Ω
	50kHz	Ζ	±2%	±1%	±1%	±2%			50kHz	R, X	±8Ω	±15Ω	±30Ω
RL	250kHz	Ζ	±2%	±2%	±2%	±2%		RL	250kHz	R, X	±8Ω	±15Ω	±30Ω
	500kHz	Ζ	±3%	±3%	±3%	±3%			500kHz	R, X	±8Ω	±15Ω	±60Ω
	1000kH	7	. 100/	. 400/	. 4 0 0 /				1000kH	R. X	. 100		c.
	z	Ζ	±10%	±10%	±10%	reference			z	,	±16Ω	±30Ω	reference
	1kHz	Ζ	±2%	±2%	±2%	±2%	1		1kHz	R. X	±8Ω	±15Ω	±30Ω
	5kHz	7	+2%	+2%	+2%	+2%			5kHz	RX	+80	+150	+300
	50kHz	7	+2%	+1%	+1%	+2%			50kHz	R X	+80	+150	+300
11	250kHz	7	±2 /0	±170	±170	±2 /0		11	250642		+80	+150	+300
		7	120/	120/	120/	120/					1002	±150	±3002
		Ζ.	±3%	±3%	±3%	±3%					±οΩ	±13Ω	±0002
	1000KH Z	Ζ	±10%	±10%	±10%	reference			TUUUKH Z	R, X	±16Ω	±30Ω	reference
	1kHz	Ζ	±2%	±2%	±2%	±2%	11		1kHz	R, X	±8Ω	±15Ω	±30Ω
	5kHz	Ζ	±2%	±2%	±2%	±2%			5kHz	R. X	±8Ω	±15Ω	±30Ω
	50kHz		+2%	+1%	+1%	+2%			50kHz	R.X	+80	+150	+300
RH	250kHz	7	+2%	+2%	+2%	+2%		RH	250kHz	RX	+80	+150	+300
	500kHz	7	+3%	+3%	+3%	+3%			500kHz	R X	+80	+150	+600
	1000kH	2	1070	1070	1070	1070			1000kH	P Y	1032	1032	10032
	Z	Z	±10%	±10%	±10%	reference			Z	П, Л	±16Ω	±30Ω	reference
	1kHz	Ζ	±2%	±2%	±2%	±2%	11		1kHz	R. X	±8Ω	±15Ω	±30Ω
	5kHz	7	+2%	+2%	+2%	+2%			5kHz	RX	+80	+150	+300
	50kHz	7	+2%	+1%	+1%	+2%			50kHz	R X	+80	+150	+300
тн	250kHz	~	+2%	+2%	+2%	+2%		ТН	250kHz	P Y	+80	+150	+300
	500kUz	7	±20/	±2 /0	+20/	+20/					+90	+150	+600
		2	±3%	±3%	±3%	±3%					TOU	±1002	±0002
	Z	Ζ	±10%	±10%	±10%	reference			Z	К, Л	±16Ω	±30Ω	reference
	1kHz	Ζ	±2%	±2%	±2%	±2%	1		1kHz	R, X	±8Ω	±15Ω	±30Ω
	5kHz	Ζ	±2%	±2%	±2%	±2%			5kHz	R. X	±8Ω	±15Ω	±30Ω
	50kHz	7	+2%	+1%	+1%	+2%			50kHz	R.X	+80	+150	+300
L-L	250kHz	7	+2%	+2%	+2%	+2%		L-L	250kHz	RX	+80	+150	+300
	500kHz	7	+3%	+3%	+3%	+3%			500kHz	R X	+80	+150	+600
	1000kH	2	1070	1070	1070	1070			1000kH	R X	±012	1032	10032
	Z	Z	±10%	±10%	±10%	reference			Z	Ν, Λ	±16Ω	±30Ω	reference
					Z: Impe	dance R	R	esistance	e X: Rea	actance			





Initial value

initial valu	Je								
The differ	The difference between EU and ASIA is only Fat% regression formula. Select Type								
			ASIA	EU					
Service	System	Fat% regression formula	Asian	Global					
mode	Oystem	Select RS5V	OFF						
		Set Printer Operation	0	Ν					
	Print	Auto Print	OFF						
		Paper	Pre Printed form						
		Adjust Printing Postion	Right:[0.0]mm、Left:[0.0]mm						
	PC Connection	Baud Rate	9600						
		Flow Control	Hardware						
Setting	Ontional Device	Input Device	OF	F					
mode	Optional Device	Card Reader length	13						
	Mossuromont	ID	OFF						
	Mode	Athletic Selection	ON						
	Wode	BF % Target Setting	BF % Target Setting ON						
		Brightness	5						
	Controller	Веер	ON						
		Vibration Mode ON		N					

2.8 C	Controller settings	
	DISPLAY	Operation
Maintenance	Maintenance 21/01/2010 Date and Time System Scale Version Impedance History Initialization Thuch Panel Exit MC-980	Select "Controller"
Controller	Controller 19/08/2010 Reghtness Beep Vignalion mage	Select setting items Initial value Brightness 5 Beep ON Vibration mode ON

3. Troubleshooting

Failure case	Check points	Repairing method
Any screen is not displayed though it turns on the main power.	Check the power supply cord connection of the main unit and the control unit	Check the cable again
	Check the power cable connection of the power source and each PCB	Check the cable again
	Check whether the power is supplied from the power source to control unit	If not supplied Change the power source If supplied Change the control unit
	Check the communication cable connection of the main PCB and the control unit	Check the cable again
	If there is no improvement by each method	Exchange the main PCB
Measurements are inaccurate Even if a standard resistance is measured, the measurements value are unstable. Measurements are too large / too small.	Check the hand grip electrode / foot electrode cable connection	Check the cable again.
	Calibrate impedance by standard resistor 200Ω , 600Ω and 1200Ω . Measure impedance with a standard resistor	if it is out of the tolerance Change the impedance PCB
	400Ω , 800Ω and 1500Ω , and confirm measurements are in the tolerance.	
	Check whether the microcomputer on the impedance PCB works with the latest version software.	if it is not the latest version Update the software
Error message are displayed "Communication error" after turning on the power of the main unit.	Check the writable mode switch of the microcomputer on the main PCB	if it is set writable mode Switch it to un-writable
	Check the writable mode switch of the microcomputer on the impedance PCB	if it is set writable mode Switch it to un-writable
	Check the solder position of an analog PCB.	Correct the soldering position
Error message are displayed Though the date and time has been set, the date setting is demanded many times.	Check whether the lithium battery is correctly set.	Set the lithium battery
	If there is no improvement by each method	Exchange the main PCB